Spacetime Discretization Methods for Numerical Relativity

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International HPC Summer School, 2018





Current approach to Numerical Relativity

- \bullet detailed, large scale numerical simulations. Required, for example, in searching for gravitational waves with LIGO.
- \bullet many cases, prohibits exploration of the full parameter space and even new physics.
- \bullet problem. They employ a finite-difference or spectral discretization in each spatial slice and evolve in time.
- Parallelism is obtained by dividing the spatial domain into \bullet patches that can be computed in parallel at each time step.
- Patches have time-like boundaries; characteristics cross in both \bullet directions. Requires inter-patch communication at every time step.
- **Communication is expensive**; in fact, probably the slowest operation in modern HPC systems.

Accurate modelling of highly dynamical, strong field astrophysical phenomena, such as binary black hole mergers require

Successful simulation of a binary black hole merger is quite recent¹. These simulations are computationally expensive; in

Most NR codes employ a 3+1 split to decompose Einstein's field equations of general relativity into a Cauchy initial value



Patches communicate boundary data on each time step.

Our approach — Spacetime Elements

- lacksquare
- Removes the need for communication at every time step, if one chooses the patch boundaries wisely; i.e. null or space-like.
- Spacetime patches only require an initial condition at the incoming patch boundaries, and the results of the computation, i.e. the outgoing patch boundaries, serve as initial conditions for the future patches.

To the right, we show a spacetime discretization of a 1+1 spacetime manifold. The patches are numbered according to causality. Patches with the same number can be solved in parallel.

- Use Discontinuous Galerkin Finite elements representation. Provides a tunable balance between achieving high work-efficiency and increased parallelism on current HPC systems.
- A simple back-of-the-envelope calculation shows one could reduce \bullet the number of communication steps by a factor of ~40 (probably too optimistic).

Use a spacetime patch. Instead of discretizing in space and time, chunk up the manifold in spacetime patches.





Ongoing Research

- Developing computational infrastructure to solve a toy model: the scalar wave equation on curved backgrounds using spacetime discretization methods.
- To get the equations of motion, start with the action, discretize, and then extremize.

$$S = \int \eta^{\alpha\beta} \nabla_{\alpha} \phi \nabla_{\beta} \phi \, d^2 x$$

$$S^N = \sum_{p,q,k,l}^{N^2} w_p w_q \, \eta_{pq}^{\alpha\beta} \, [D_{\alpha}]_l^p \, \phi^l \, [D_{\beta}]_m^p \, \phi^m \longrightarrow S^N = \phi^{\mathrm{T}} \mathbf{L} \, \phi$$

• Using Futures in julia

to asynchronously compute multiple spacetime patches concurrently. Abstracts away the complexity behind explicit message passing between patches.

Define patchⁿ⁺¹ = Future of (patchⁿ L + patchⁿ R)



A spacetime perturbation propagating in 1+1 Minkowski spacetime. Using 16 patches in total, with 20 points along each direction in each patch.

Future Extensions

- Extend the infrastructure to be able to handle higher dimensional problems, concretely 3+1 for classical \bullet gravity.
- Use an unstructured mesh spacetime elements will now be higher order simplexes. Would allow \bullet for more flexibility to adapt the grid to the problem. Useful, for example, to study the structure of apparent horizons near merger.
- For unstructured meshes, given a tessellation on an initial hyper \bullet surface, the mesh front can be advanced in time using the tentpitching algorithm proposed by Üngör et. al. 2000².
- Unstructured grid usually considered to be less efficient due to \bullet the overhead of managing mesh connectivity. However, use of higher order polynomials in each element or clubbing multiple elements together can amortize this cost.
- Work with conformally compactified domains. Removes the need \bullet for an artificial outer-boundary, and provides a clean way to extract radiation at null infinity.



Figure 1.6 from Shripad Thite, Spacetime meshing for Discontinuous Galerkin *methods.* Given a 2D tessellation, the algorithm constructs a tetrahedral spacetime mesh.

