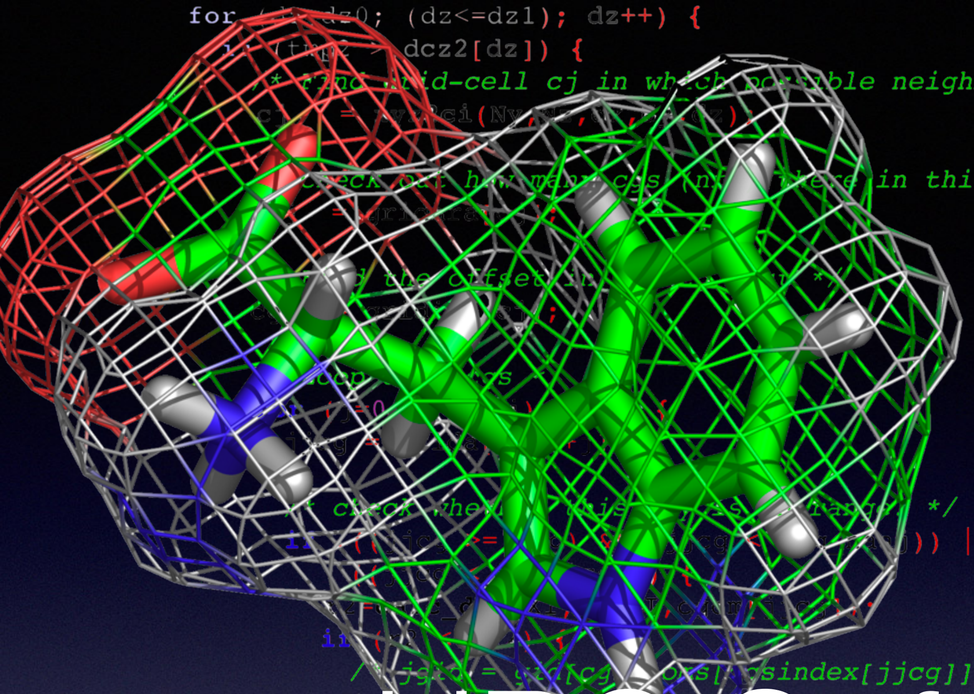


HPC Software Engineering

Erik Lindahl

XSEDE/PRACE/RIKEN/SciNet HPC Summer School Ostrava, CZ, 2018

Extra Q & A session: Here (or outside at the tables) 12.45 today!

SciLifeLab STOCKHOLM

UNIVERSITET STOCKHOLMS

KTH VETENSKAP OCH KONST

“The application of a systematic, disciplined, quantifiable approach to the development, operation and maintenance of software, and the study of these approaches, that is, the application of engineering to software.”

Experiences from 20 years of GROMACS development

- Simulation *hardware* project, turned software
- Early development based on our own needs
- Turned GPL in 2001, LGPL in 2012
- Organic growth of development
  - Roughly 10-15 core developers
  - Another 15-20 active contributors
- Currently 3,076,420 lines of C++11 code (“C++11”)
  - Over the years we have used Fortran, C, Assembly
- Lots of old code. Lots of new code. Lots of complicated (read: bad) code written by scientists

The GROMACS picture until early 2011

Source code repository:

CVS

Build Chain:

Automake/Autoconf/libtool

Bug Tracking:

Bugzilla

Testing:

Scientist

- Trained in physics, chemistry, etc.
- Care about their problem
- Care about short-term deadlines
- New code = asset
- Writes more code than she reads

Software engineer

- Trained in CS/software
- Care about their code
- Care about long-term maintenance
- New code = liability
- Reads much more code than she writes

Without proper software engineering, we are building a technical debt that sooner or later will have to be paid.

"Technical Debt is a wonderful metaphor developed by Ward Cunningham to help us think about this problem. In this metaphor, doing things the quick and dirty way sets us up with a technical debt, which is similar to a financial debt. Like a financial debt, the ***technical debt incurs interest payments****, which come in the form of the extra effort that we have to do in future development because of the quick and dirty design choice. We can choose to* ***continue paying the interest, or we can pay down the principal by refactoring*** *the quick and dirty design into the better design. Although it costs to pay down the principal, we gain by reduced interest payments in the future."*

[Martin Fowler]

Professional modern development tools

… with illustrations from GROMACS, and a new example based on the IHPCSS Laplace example code!

What changed in our code between IHPCSS 2015 & 2016?
(Basically the difference between GROMACS-5.1 and GROMACS 2016)

957 commits

4163 files changed

393,488 line insertions

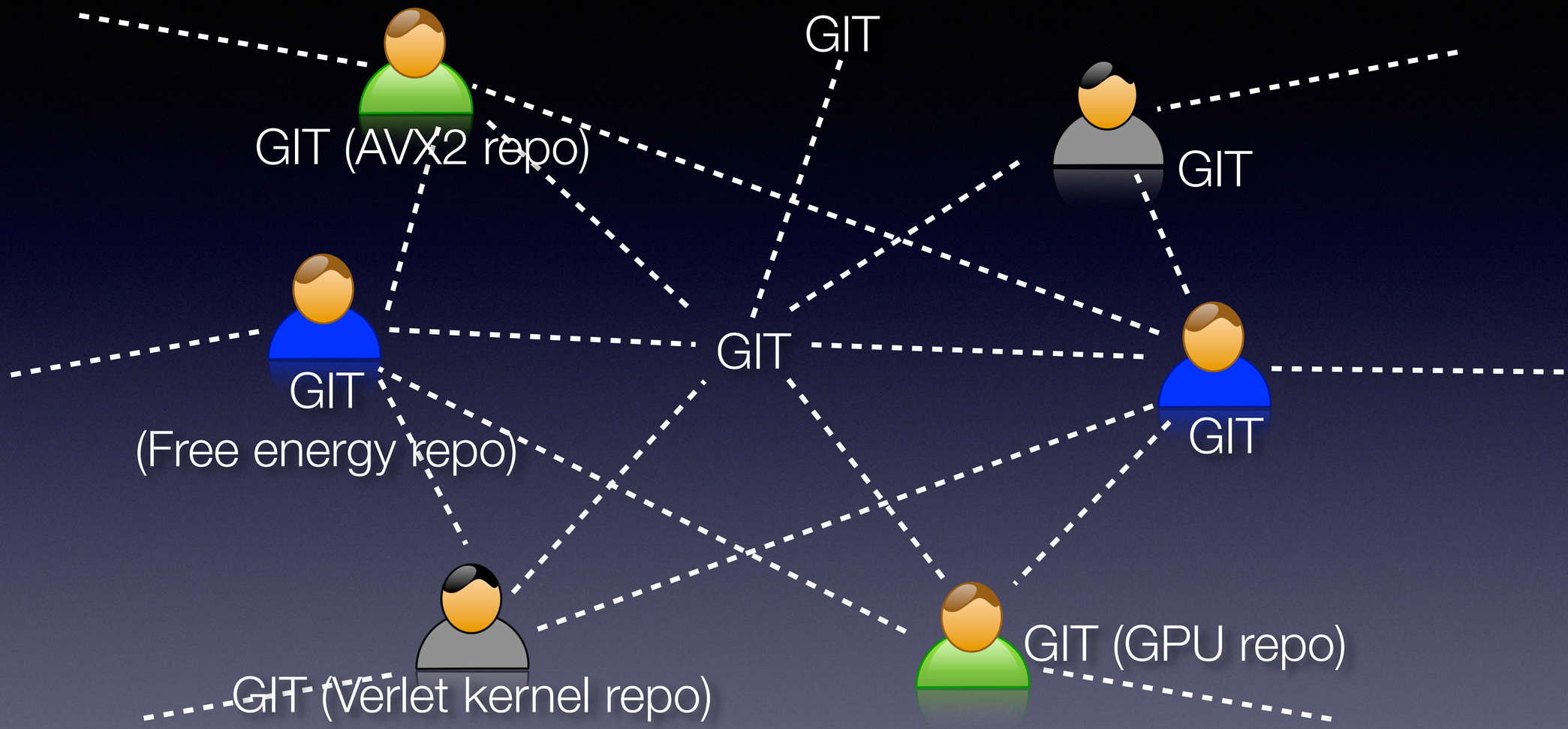
373,227 line deletions

How would you start debugging if the new version crashes?

You have probably all seen this: Your program worked an hour ago, but with the latest edits there is something wrong

What if it crashes with “-O3”, but when you try to debug it works fine?

Better source control: GIT



Free hosting available e.g. at github.com

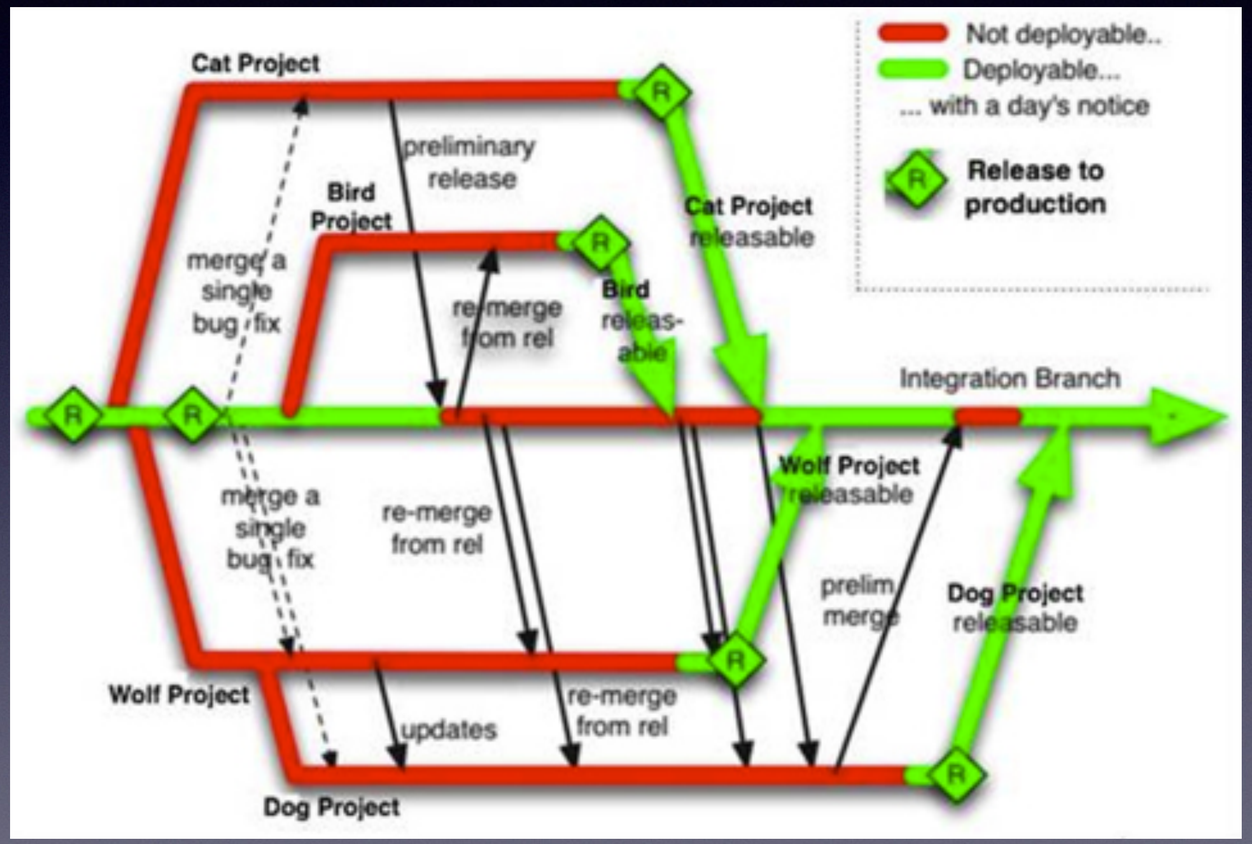
New example software engineering project for you to play around with:
https://github.com/IHPCSS/software-engineering

What git will give you

- Handles multiple developers beautifully
- Handles multiple feature branches in parallel with a stable production-quality one
- Develop based on features, not source files
- Pull/push patches between branches
- Revert a specific stupid thing I did 6 months ago, without changing subsequent patches
- Bisect changes to find which one of (say) 1,500 patches caused a bug

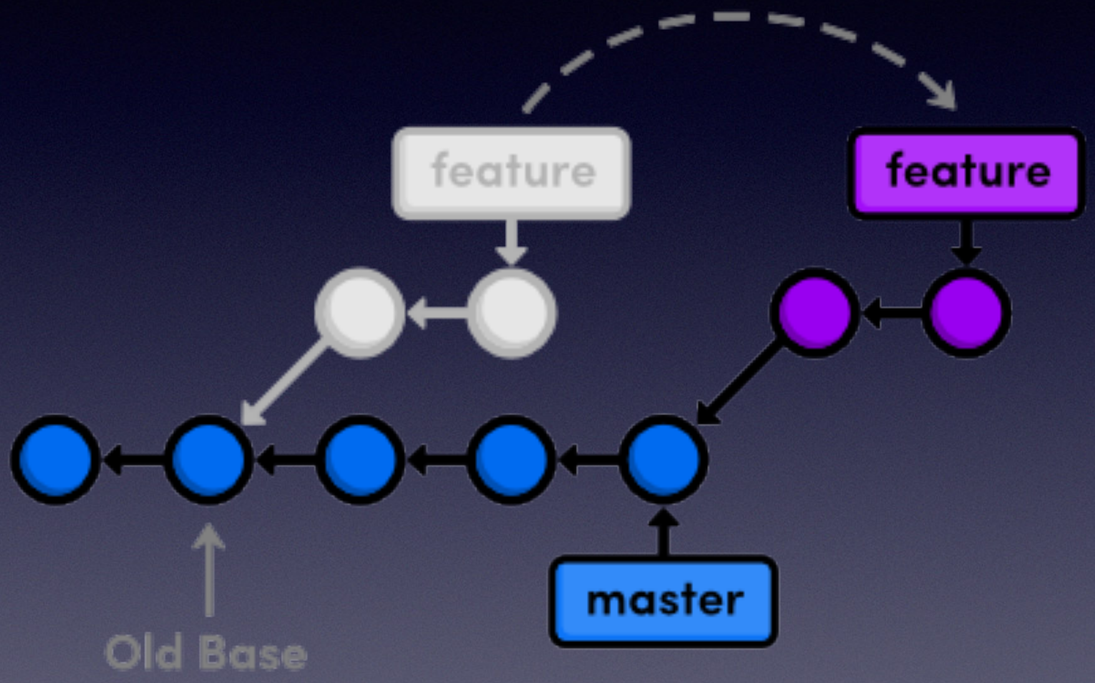
Drawback: Git is a VERY powerful tool, but the advanced features can be difficult to understand

One Possible Git Workflow: Multiple branches & merging



- Each feature is a new branch
- Think of the hybrid challenge:
  - Common base is the scalar version
  - Feature 1: MPI
  - Feature 2: OpenMP
  - Feature 3: OpenACC
- Imagine that these features have now been developed/improved over 3 months.
- **Each feature branch works great, but major pains when you need to combine them & release**

Better approach: (Constant) rebasing



- Think of feature commits as work-in-progress (e.g. on my laptop) that have not yet made it into our common master branch
- A large project like GROMACS can have hundreds of such work-in-progress commits; each of them is independent of all other feature commits
- **When one feature commit is ready & merged into master, the other features should rebase to instead be a difference relative to the updated master state**
- You *can* continue to work with the old base while developing, but before committing your feature it has to be rebased
- Advantage: Clean changes, rapid deployment

Good git commits are

- Small (think 10-100 lines, not 1000)
- Decomposed as far as possible
- Limited to address a single issue
- Well documented
- Tested to work

This type of commits will also be close to trivial to rebase!

Have a look at some of the commits in the IHPCSS-laplace repo!

Is your code portable?

Does your code compile on
windows (MSVC)?
PGI Compilers? Pathscale?
Blue Gene?
K computer (Fujitsu compilers)?
ARM? AArch64?
PowerPC (big endian)?
Google NativeClient?
OpenPower (little endian?)

What is a build chain?

The typical user progression:

- Issue compiler commands manually
- Start using Makefiles, edit Makefiles, give up
- Automate the generation of Makefiles

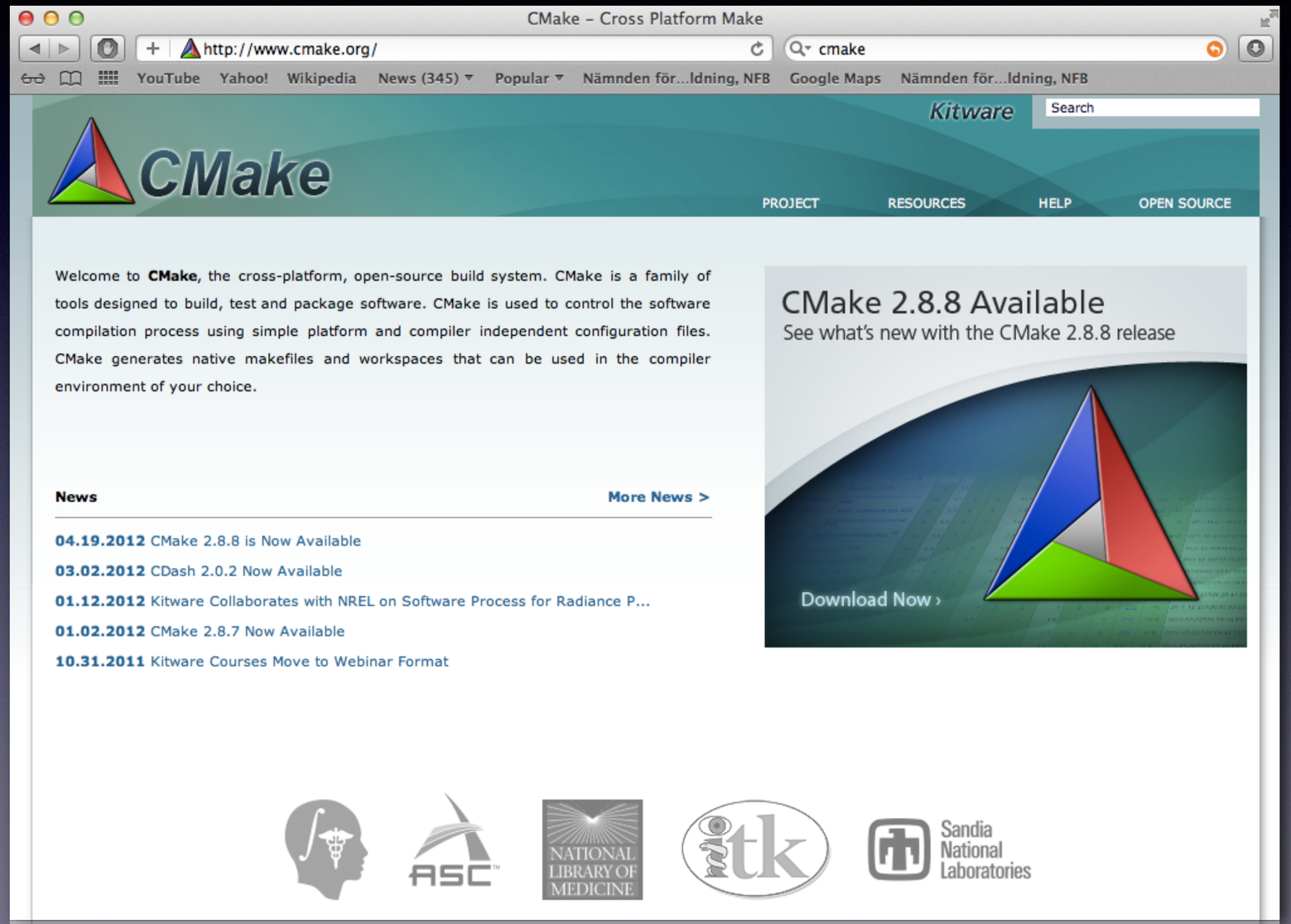
Friends don’t let friends use GNU autotools…

Configuration

- “Where is the X11 library? MKL? LibXML?”
- “What version is the FFTW library?”
- “Is the Intel Math Kernel Library installed?”
- “Do we use that buggy gcc version?”
- “Does this compiler understand Xeon Phi AVX512?”
- “Which flags should be used to enable C++11 for this compiler?”
- “Is this a big or small endian system?”
- “Is a long integer 4 or 8 bytes on this host?”
- “How do we build a shared library here?”
- “How do we turn on OpenMP? OpenACC?”
- “What library should I link with to have gettimeofday() available?”
- “What C backend compiler is used with CUDA-8.0?”
- “What underscore naming standard does this Fortran compiler use?”
- “Is Doxygen available? Sphinx? Dot?”

CMake: Cross-platform replacement for Autoconf, Automake, Libtool

(instead of ./configure; make; make install)



GROMACS has ~100 CMake tests for features/bugs/libraries/compilers

- CheckCCompilerFlag.cmake
- CheckCXXCompilerFlag.cmake
- cmake_uninstall.cmake.in
- FindEXTRAE.cmake
- FindFFTW.cmake
- FindVMD.cmake
- gmxBuildTypeProfile.cmake
- gmxBuildTypeReference.cmake
- gmxBuildTypeReleaseWithAssert.cmake
- gmxBuildTypeThreadSanitizer.cmake
- gmxCFlags.cmake
- gmxDetectClang30.cmake
- gmxDetectGpu.cmake
- gmxDetectSimd.cmake
- gmxDetectTargetArchitecture.cmake
- gmxFindFlagsForSource.cmake
- gmxGCC44O3BugWorkaround.cmake
- gmxGenerateVersionInfo.cmake
- gmxManageBlueGene.cmake
- gmxManageFFTLibraries.cmake
- gmxManageGPU.cmake
- gmxManageLinearAlgebraLibraries.cmake
- gmxManageMPI.cmake
- gmxManageNvccConfig.cmake
- gmxManageOpenMP.cmake
- gmxManageSharedLibraries.cmake
- gmxManageSuffixes.cmake
- gmxOptionUtilities.cmake
- gmxSetBuildInformation.cmake
- gmxTestAVXMaskload.cmake
- gmxTestCatamount.cmake
- gmxTestCompilerProblems.cmake
- gmxTestCXX11.cmake
- gmxTestdlopen.cmake
- gmxTestFloatFormat.cmake
- gmxTestInlineASM.cmake
- gmxTestIsfinite.cmake
- gmxTestLargeFiles.cmake
- gmxTestLibXml2.cmake
- gmxTestMPI_IN_PLACE.cmake

```
MACRO(GMX_TEST_AVX_GCC_MASKLOAD_BUG VARIABLE AVX_CFLAGS)
    IF(NOT DEFINED ${VARIABLE})
        MESSAGE(STATUS "Checking for gcc AVX maskload bug")
        # some compilers like clang accept both cases,
        # so first try a normal compile to avoid flagging those as buggy.
        TRY_COMPILE(${VARIABLE}_COMPILEOK "${CMAKE_BINARY_DIR}"
                    "${CMAKE_SOURCE_DIR}/cmake/TestAVXMaskload.c"
                    COMPILE_DEFINITIONS "${AVX_CFLAGS}" )
        IF(${VARIABLE}_COMPILEOK)
            SET(${VARIABLE} 0 CACHE INTERNAL "Work around GCC bug in AVX maskload argument" FORCE)
            MESSAGE(STATUS "Checking for gcc AVX maskload bug - not present")
        ELSE()
            TRY_COMPILE(${VARIABLE}_COMPILEOK "${CMAKE_BINARY_DIR}"
                        "${CMAKE_SOURCE_DIR}/cmake/TestAVXMaskload.c"
                         COMPILE_DEFINITIONS "${AVX_CFLAGS} -DGMX_SIMD_X86_AVX_GCC_MASKLOAD_BUG" )
            IF(${VARIABLE}_COMPILEOK)
                SET(${VARIABLE} 1 CACHE INTERNAL "Work around GCC bug in AVX maskload argument" FORCE)
                MESSAGE(STATUS "Checking for gcc AVX maskload bug - found, will try to work around")
            ELSE()
                MESSAGE(WARNING "Cannot compile AVX code - assuming gcc AVX maskload bug not present." )
                MESSAGE(STATUS "Checking for gcc AVX maskload bug - not present")
            ENDIF()
        ENDIF()
    ENDIF()
ENDMACRO()
```

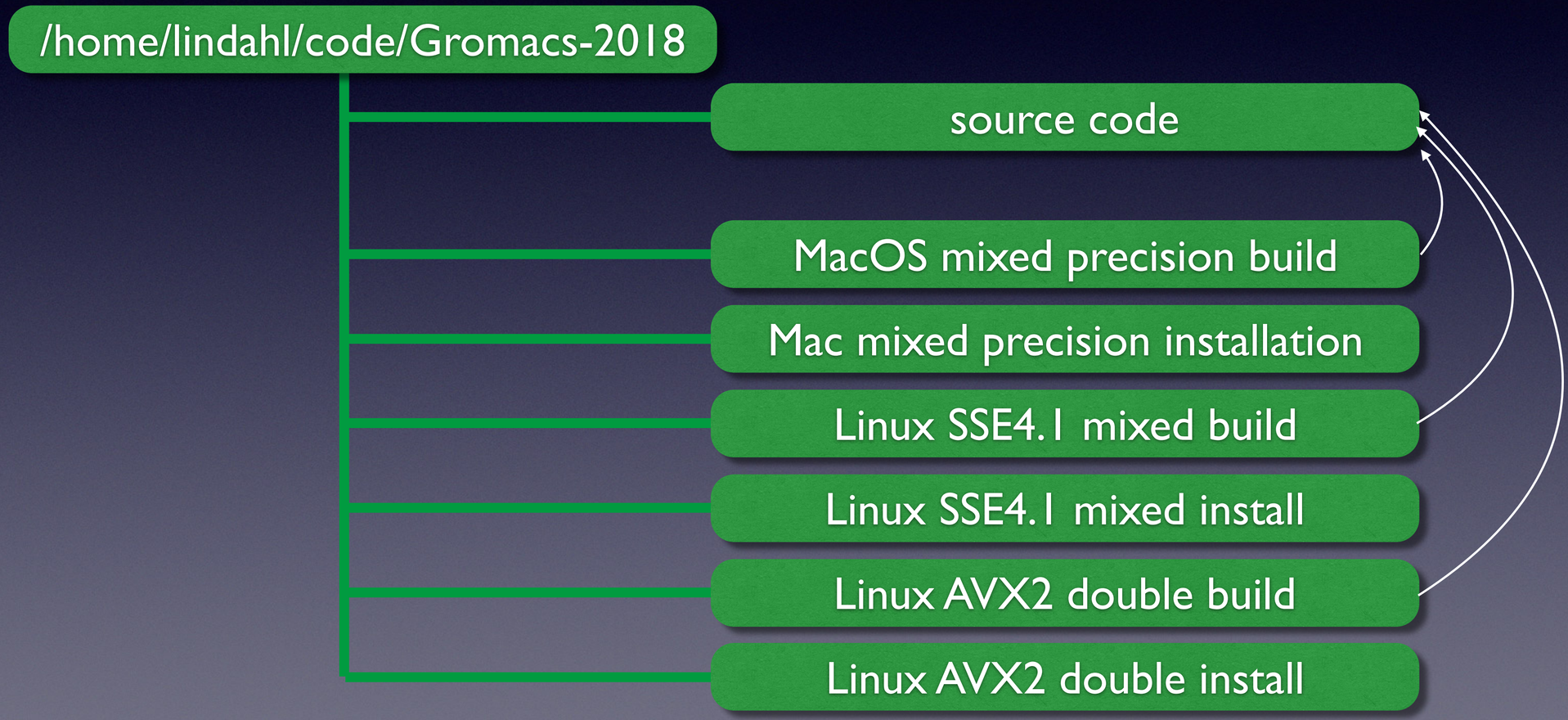
Optional components (FFT libs) and extensive regressiontests can be downloaded automatically

Generators: Makefiles, Eclipse, Xcode,
VisualStudio, nmake, CodeBlocks, KDevelop3, etc.

But don’t start with GROMACS: Look at the CMakeLists.txt in the IHPCSS/software-engineering example: ~30 lines, a few source subdirectories, and 3-4 modules in the cmake subdirectory.

Out-of-source builds

Don’t put the build objects inside the source code directory!



Make a small change, run “make” in three build directories, done.

decades

Living with your code for ~~years~~:

Documentation

Direct source code documentation should stay in the source!

Doxygen example - our SIMD module: [gromacs/src/gromacs/simd/]

```
49  #ifndef GMX_SIMD_SIMD_H
50  #define GMX_SIMD_SIMD_H
51
52  /*! \libinternal \file
53   *
54   * \brief Definitions, capabilities, and wrappers for SIMD module.
55   *
56   * The macros in this file are intended to be used for writing
57   * architecture-independent SIMD intrinsics code.
58   * To support a new architecture, adding a new sub-include with macros here
59   * should be (nearly) all that is needed.
60   *
61   * The defines in this top-level file will set default Gromacs real precision
62   * operations to either single or double precision based on whether
63   * GMX_DOUBLE is defined. The actual implementation - including e.g.
64   * conversion operations specifically between single and double - is documented
65   * in impl_reference.h.
66   *
67   * \author Erik Lindahl <erik.lindahl@scilifelab.se>
68   *
69   * \inlibraryapi
70   * \ingroup module_simd
71   */
72
73  #ifdef HAVE_CONFIG_H
74  #include <config.h>
75  #endif
76
77  #include <stddef.h>
78
```

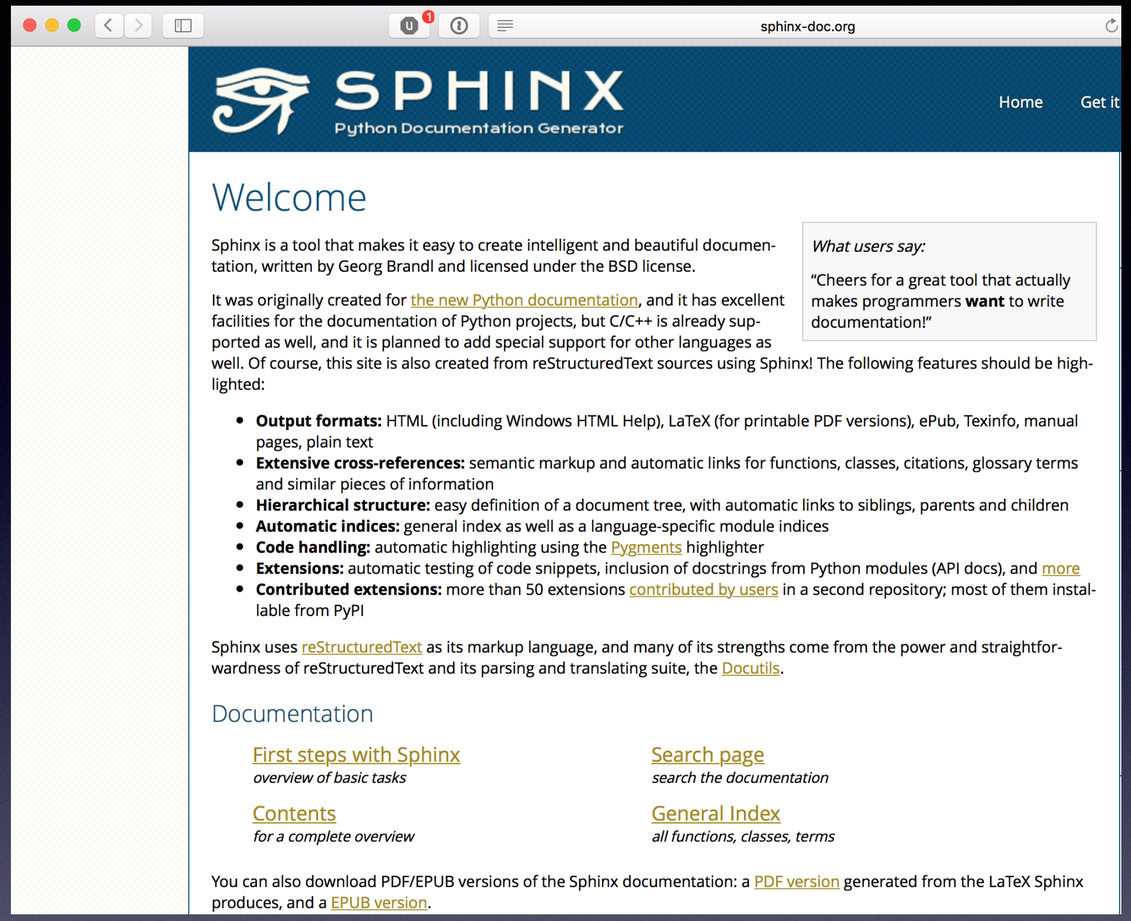
```
155 /*! \brief
156  * Align a float pointer for usage with SIMD instructions.
157  *
158  * You should typically \a not call this function directly (unless you explicitly
159  * want single precision even when GMX_DOUBLE is set), but use the
160  * \ref gmx_simd_align_r macro to align memory in default Gromacs real precision.
161  *
162  * \param  p Pointer to memory, allocate at least \ref GMX_SIMD_FLOAT_WIDTH extra
163  *
164  * \return Aligned pointer (>=p) suitable for loading/storing float fp SIMD.
165  *         If \ref GMX_SIMD_HAVE_FLOAT is not set, p will be returned unchanged.
166  *
167  * Start by allocating an extra \ref GMX_SIMD_FLOAT_WIDTH float elements of memory
168  * and then call this function. The returned pointer will be greater or equal
169  * to the one you provided, and point to an address inside your provided memory
170  * that is aligned to the SIMD width.
171  */
172 static gmx_inline float *
173 gmx_simd_align_f(float *p)
174 {
175 #    ifdef GMX_SIMD_HAVE_FLOAT
176     return (float *)(((size_t)((p)+GMX_SIMD_FLOAT_WIDTH-1)) & (~((size_t)
            (GMX_SIMD_FLOAT_WIDTH*sizeof(float)-1))));
177 #    else
178     return p;
179 #    endif
180 }
181
```

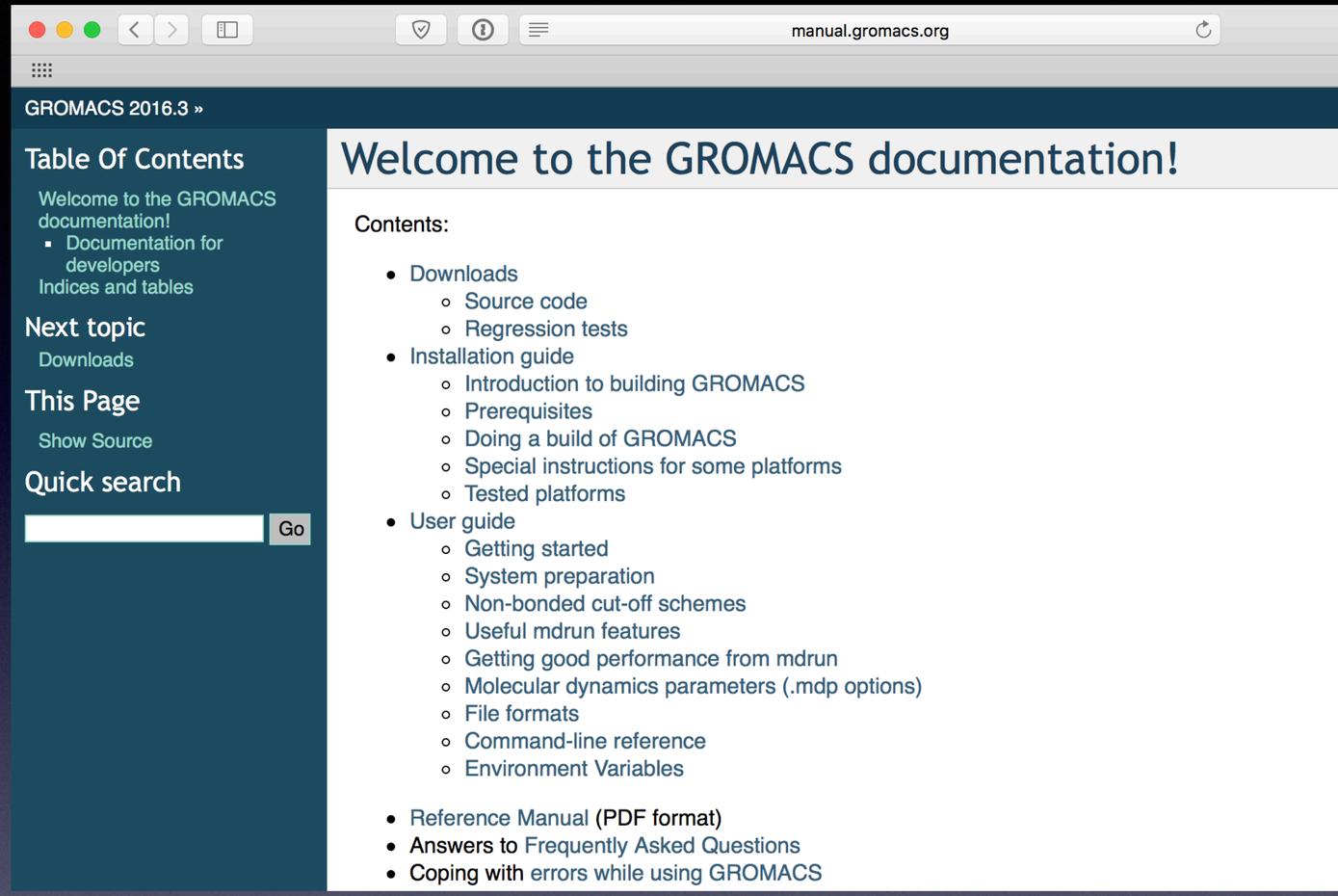
The best comments don’t explain what your code does, they explain WHY you do it this way!

For humorous counter-examples, Google “how to write unmaintainable code pdf”

The IHPCSS/software-engineering example comes with full Doxygen integration - but we have not yet had time to document the code! CMake finds “doxygen” automatically so you can do “make doxygen”

High level non-source-code documentation: SPHINX (from Python)





Also fully integrated into IHPCSS-laplace. Check out the docs folder, and if you have sphinx/latex installed you can type “make sphinx-html” or “make sphinx-pdf”.

… and we have integrated it with readthedocs.org! Any time a new change is pushed to the gibhub repo, documentation is built automatically at http://software-engineering.readthedocs.org

Finding & Preventing Bugs

Modularization

- Avoid code inter-dependencies
- Have modules doing clearly separate tasks
- Make sure all code is thread-safe!
- Have a clear (documented) API for each module
- Write unit tests, not only regression tests
- Design-for-Testability (DFT):
  Write unit test first, then the code implementation

Controversial (?): Move to C++

Languages?

- “REAL PROGRAMMERS CAN WRITE FORTRAN IN ANY LANGUAGE”
- "C combines the flexibility and power of assembly language with the user-friendliness of assembly language."
- “C makes it easy to shoot yourself in the foot; C++ makes it harder, but when you do it blows your whole leg off.”
- The actual C++ nightmare: *You accidentally create a dozen instances of yourself and shoot them all in the foot. Providing emergency medical care is impossible since you can't tell which are bitwise copies and which are just pointing at others and saying, "That's me over there."*

C++ Core guidelines (Herb Sutter & Bjarne Stroustrup):
https://github.com/isocpp/CppCoreGuidelines/blob/master/CppCoreGuidelines.md

The Case for C++

Modern: Threads, atomics, etc. part of C++11

Very powerful library with containers, algorithms

Strongly typed language

Still a low-level language - you control data exactly

Modern C++ has gotten rid of pointers, memory errors

Templates avoid code duplication

Some very advanced parallelization libraries: Intel TBB

Rapidly developing language, large ISO committee

Negative: It is a VERY complex language to master

Example: If you have ever worked with mutex:es to make sure only one thread accesses a critical region, you have likely bumped into race conditions or deadlocks e.g. when you forget to release a mutex in complex code.
These errors are insanely difficult to debug, since it depends in dynamic timing events - when you run it in the debugger there won't be any error!

Definition:

```
class Lock {
public:
    explicit Lock(Mutex *pm)
    : mutexPtr(pm)
    { lock(*mutexPtr); }

    ~Lock() { unlock(*mutexPtr) };

private:
    Mutex *mutexPtr;
}
```

Usage in client code:

```
Mutex m;

…

{
    Lock ml(&m);
    …
}
```

One more problem: What happens if you copy that class? Then the first object to go out of scope will release the mutex, while the second thinks it's still locked (=bad)!

Easy to fix in C++11: Just use a reference-counted shared pointer.
Note: no change to the client code.

Definition:

```
class Lock {
public:
    explicit Lock(Mutex *pm)
    : mutexPtr(pm, unlock)
    { lock(mutexPtr.get()); }

    ~Lock() { unlock(*mutexPtr) };

private:
    std::shared_ptr<Mutex> mutexPtr;
}
```

Usage in client code:

```
Mutex m;

…

{
    Lock ml(&m);
    …
}
```

Surprise: C++ can be (much) faster than FORTRAN or C!

C/FORTRAN

```
int
myFunc(obj_t obj, int choiceA, int choice B)
{
    for(int i=0;i<obj.N;i++)
    {
        if(choiceA==1)
        {
            if(choiceB==1)
            {
                kernelcode1;
            }
            else if(choiceB==2)
            {
                kernelcode2;
            }
        }
        else if(choiceA==2)
        {
            if(choiceB==1)
            {
                kernelcode3;
            }
            else if(choiceB==2)
            {
                kernelcode4;
            }
        }
    }
}


calling code in different translation unit:


myFunc(obj,2,3);
```

C++11

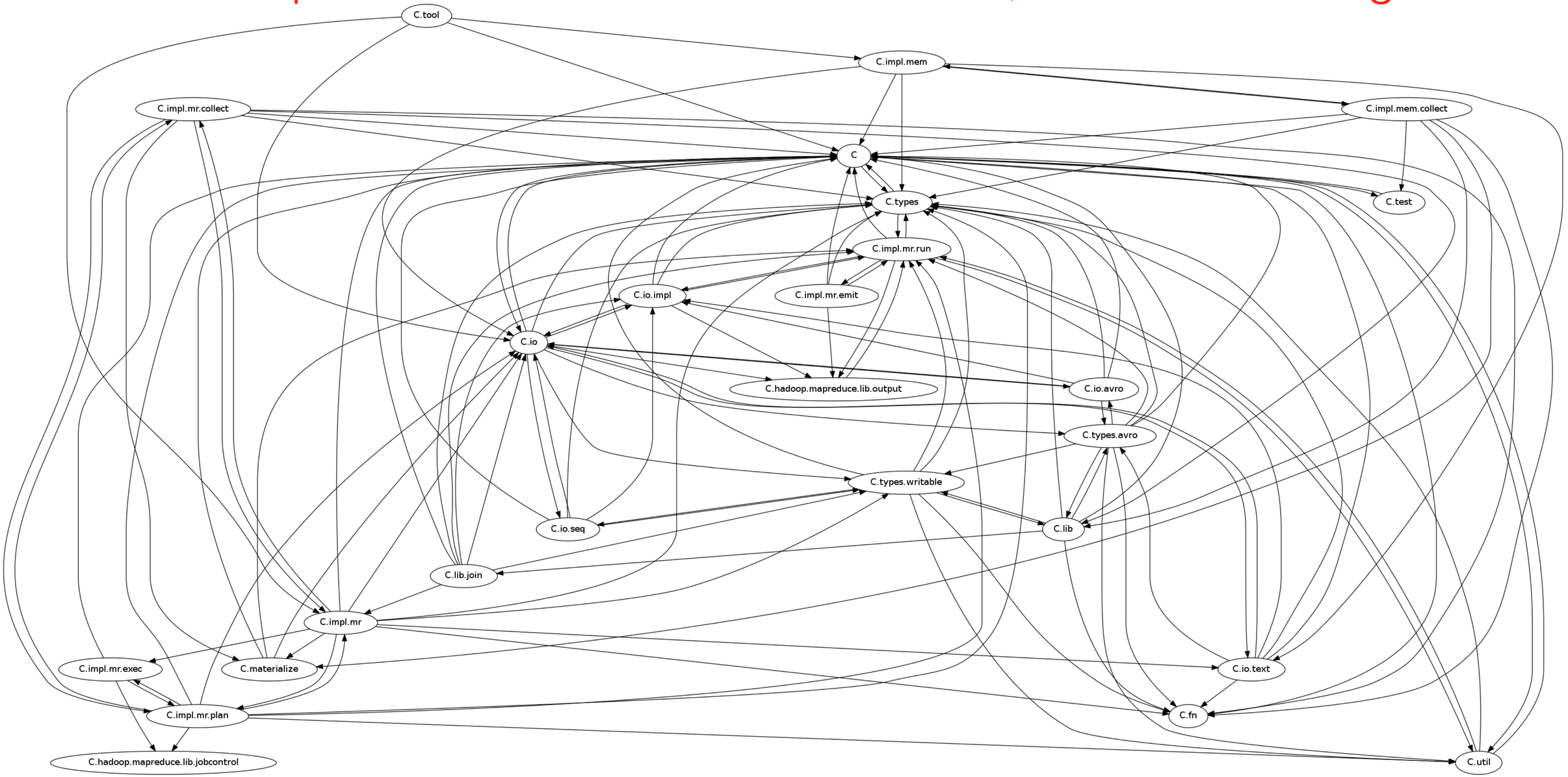
```
template <int choiceA, int choice B>
int
myFunc(obj_t obj)
{
    for(int i=0;i<obj.N;i++)
    {
        if(choiceA==1)
        {
            if(choiceB==1)
            {
                kernelcode1;
            }
            else if(choiceB==2)
            {
                kernelcode2;
            }
        }
        else if(choiceA==2)
        {
            if(choiceB==1)
            {
                kernelcode3;
            }
            else if(choiceB==2)
            {
                kernelcode4;
            }
        }
    }
}


calling code in different translation unit:

extern template int myFunc<2,3>(obj_t obj)
myFunc<2,3>(obj);
```

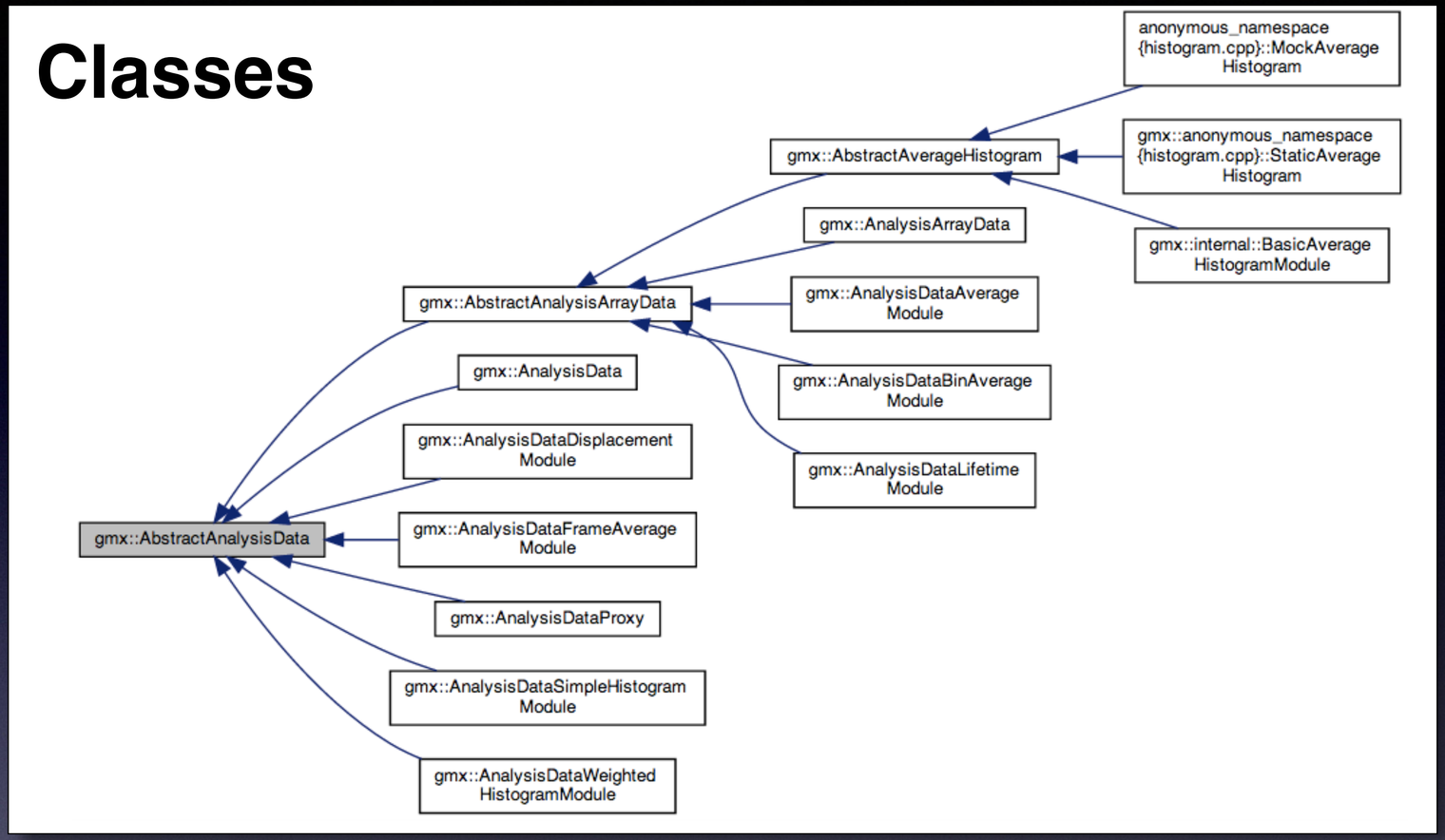
This C++ code will be fully expanded by the compiler. No conditionals present in the generated assembly code.

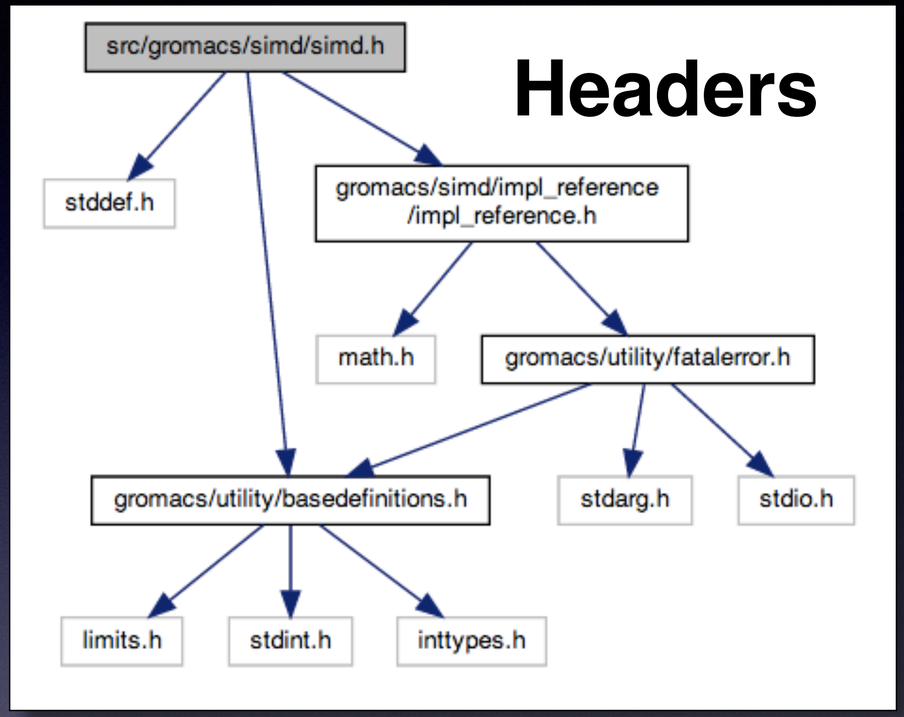
Circular dependencies are bad. If a test fails, where is the bug here?



"It has been discovered that C++ provides a remarkable facility for concealing the trivial details of a program - such as where its bugs are." (David Keppel)

Modularization: Just say ‘no’ to circular dependencies





This is hard, but Doxygen helps you detect it!

For our project (GROMACS), our code management system will not allow any developer to submit a file with a circular dependency.

googletest - Google C++ Testing Framework - Google Project Hosting

https code.google.com/p/googletest/

Umeå Univer...mi i Skolan | How to Do ...n — Medium | Computation...gy Council | Varför denna...naljapen.se | How to make...s Technica | Low Resolut...lar Domains | Examining p...Med

erik.lindahl@gmail.com ▼ | My favorites ▼

Aggressive unit testing: "Trust, but verify"

googletest
Google C++ Testing Framework

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Project Information

Starred by 2339 users
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Code license
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Labels
Cplusplus, Testing, Framework, Tests, Unittests, Cpp, Google

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8 committers

Featured

Downloads
gtest-1.7.0.zip

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Google's framework for writing C++ tests on a variety of platforms (Linux, Mac OS X, Windows, Cygwin, Windows CE, and Symbian). Based on the xUnit architecture. Supports automatic test discovery, a rich set of assertions, user-defined assertions, death tests, fatal and non-fatal failures, value- and type-parameterized tests, various options for running the tests, and XML test report generation.

Getting Started ¶

After downloading Google Test, unpack it, read the README file and the documentation wiki pages (listed on the right side of this front page).

Who Is Using Google Test?

In addition to many internal projects at Google, Google Test is also used by the following notable projects:

- The Chromium projects (behind the Chrome browser and Chrome OS)
- The LLVM compiler
- Protocol Buffers (Google's data interchange format)

If you know of a project that's using Google Test and want it to be listed here, please let `googletestframework@googlegroups.com` know.

Google Test-related open source projects

Google Test UI is test runner that runs your test binary, allows you to track its progress via a progress bar, and displays a list of test failures. Clicking on one shows failure text. Google Test UI is written in C#.

Example Gromacs unit tests:
The idea is that you should test *everything*

```
185 TEST_P(FFTTest1D, Real)
186 {
187     const int rx = GetParam();
188     const int cx = (rx/2+1);
189     ASSERT_LE(cx*2, static_cast<int>(sizeof(inputdata)/sizeof(real)));
190
191     in_  = std::vector<real>(inputdata, inputdata+cx*2);
192     out_ = std::vector<real>(cx*2);
193     real* in  = &in_[0];
194     real* out = &out_[0];
195
196     gmx_fft_init_1d_real(&fft_, rx, flags_);
197
198     gmx_fft_1d_real(fft_, GMX_FFT_REAL_TO_COMPLEX, in, out);
199     checker_.checkSequenceArray(cx*2, out, "forward");
200     gmx_fft_1d_real(fft_, GMX_FFT_COMPLEX_TO_REAL, in, out);
201     checker_.checkSequenceArray(rx, out, "backward");
202 }
```

```
204 TEST_F(SimdFloatingpointTest, gmxSimdGetMantissaR)
205 {
206     GMX_EXPECT_SIMD_REAL_EQ(setSimdRealFrom3R(1.219097320577810839026256,
207                                               1.166738027848349235071623,
208                                               1.168904015004464724825084), gmx_simd_get_mantissa_r(rSimd_Exp));
209 #if (defined GMX_SIMD_HAVE_DOUBLE) && (defined GMX_DOUBLE)
210     GMX_EXPECT_SIMD_REAL_EQ(setSimdRealFrom3R(1.241261238952345623563251,
211                                               1.047294723759123852359232,
212                                               1.856066204750275957395734), gmx_simd_get_mantissa_r(rSimd_ExpDouble));
213 #endif
214 }
215
216 TEST_F(SimdFloatingpointTest, gmxSimdSetExponentR)
217 {
218     gmx_simd_real_t x0 = setSimdRealFrom3R(0.5, 11.5, 99.5);
219     gmx_simd_real_t x1 = setSimdRealFrom3R(-0.5, -11.5, -99.5);
220
221     GMX_EXPECT_SIMD_REAL_EQ(setSimdRealFrom3R(pow(2.0, 60.0), pow(2.0, -41.0), pow(2.0, 54.0)),
222                             gmx_simd_set_exponent_r(setSimdRealFrom3R(60.0, -41.0, 54.0)));
223 #if (defined GMX_SIMD_HAVE_DOUBLE) && (defined GMX_DOUBLE)
224     GMX_EXPECT_SIMD_REAL_EQ(setSimdRealFrom3R(pow(2.0, 587.0), pow(2.0, -462.0), pow(2.0, 672.0)),
225                             gmx_simd_set_exponent_r(setSimdRealFrom3R(587.0, -462.0, 672.0)));
226 #endif
227     /* Rounding mode in gmx_simd_set_exponent_r() must be consistent with gmx_simd_round_r() */
228     GMX_EXPECT_SIMD_REAL_EQ(gmx_simd_set_exponent_r(gmx_simd_round_r(x0)), gmx_simd_set_exponent_r(x0));
229     GMX_EXPECT_SIMD_REAL_EQ(gmx_simd_set_exponent_r(gmx_simd_round_r(x1)), gmx_simd_set_exponent_r(x1));
230 }
```

Do you think it's overkill to test that hardware rounding works? In March 2014, this very test caught that IBM Power7 VMX uses different rounding modes for SIMD and normal floating-point to integer conversions…

Spring 2018: Our unit tests caught that IBM had semi-silently had to change their *binary* ABI for Power8/9 since their compiler specifications partly violated the C++ standard. Fedora running all our unit tests caught it immediately, and a few hours later we had a workaround in the code.

Good unit tests should isolate bugs to *tiny* parts of your code
In C++, each method in a class should ideally have exhaustive unit tests

```
TEST(NormalDistributionTest, Output)
{
    gmx::test::TestReferenceData        data;
    gmx::test::TestReferenceChecker     checker(data.rootChecker());

    gmx::ThreeFry2x64<8>                rng(123456, gmx::RandomDomain::Other);
    gmx::NormalDistribution<real>       dist(2.0, 5.0);
    std::vector<real>                   result;

    for (int i = 0; i < 10; i++)
    {
        result.push_back(dist(rng));
    }
    checker.checkSequence(result.begin(), result.end(), "NormalDistribution");
}
```

Are *you* aware of the peculiarities of rounding differences depending on whether your CPU hardware uses fused multiply-add (FMA) vs. separate multiply & add?

Test that a simple call to a normal distribution random generator returns the expected 10 numbers.

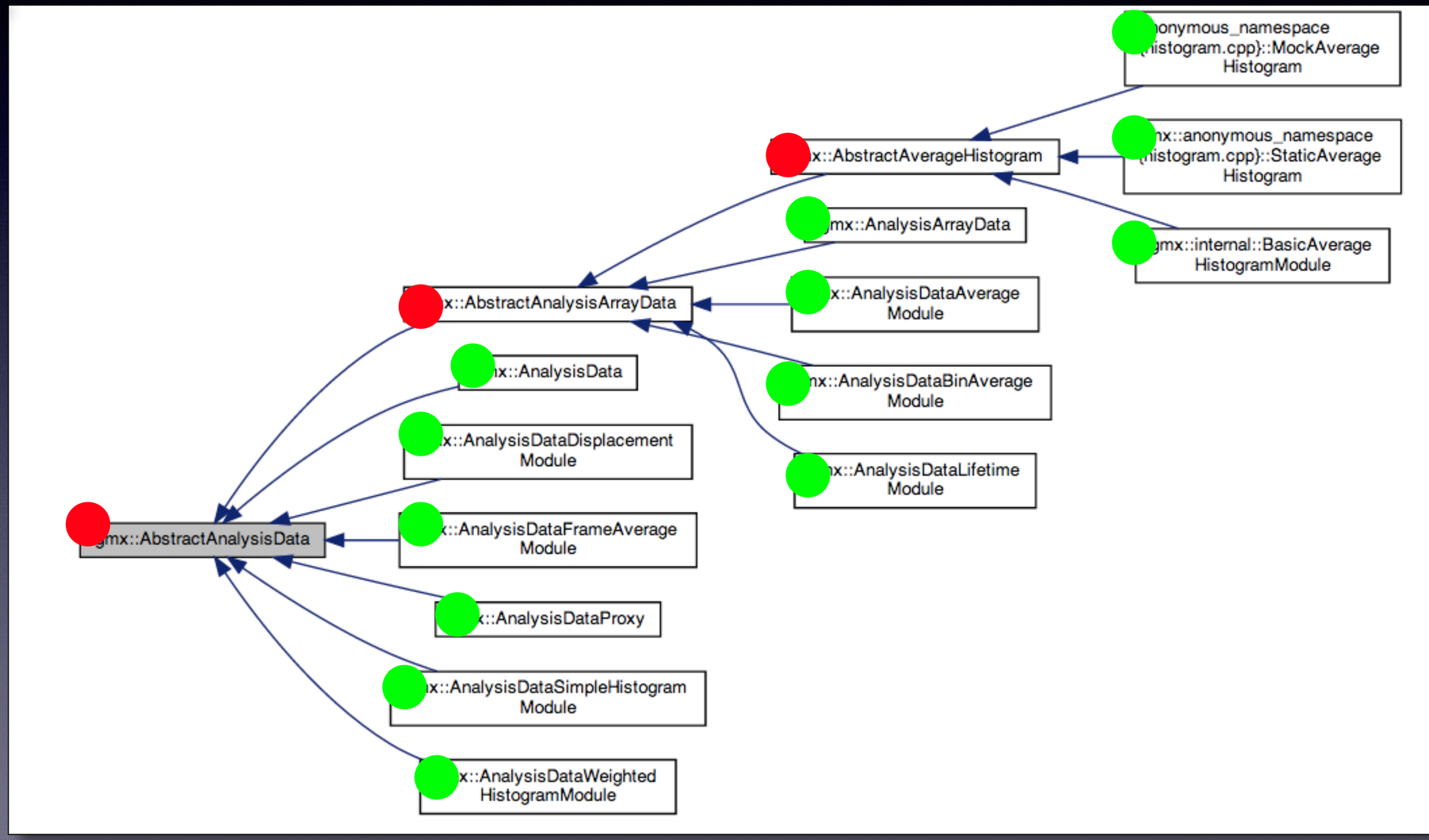
Why? Because we found that libstdc++ and libcxx do not use the same algorithm, so code will not produce the same results. We need to use our own algorithm - make sure it keeps working.

No need to ask: Of course we have integrated GoogleTest support into the IHPCSS/software-engineering repo - but since I only started working on it this Tuesday I have not had time to write the actual tests yet. However, as you add more tests, they will all execute if you just issue “make check”.

Imagine a project with ~1000 classes, and that the class diagram below is a small excerpt (it's from Gromacs).

All classes have close-to-exhaustive unit tests - but your latest build now fails the unit test.
Green means the unit test for this class was OK, red means it failed.

Where do you look for the bug?



If each unit test targets a small method/function, you have isolated the bug to within ~50 lines-of-code before even opening your editor.

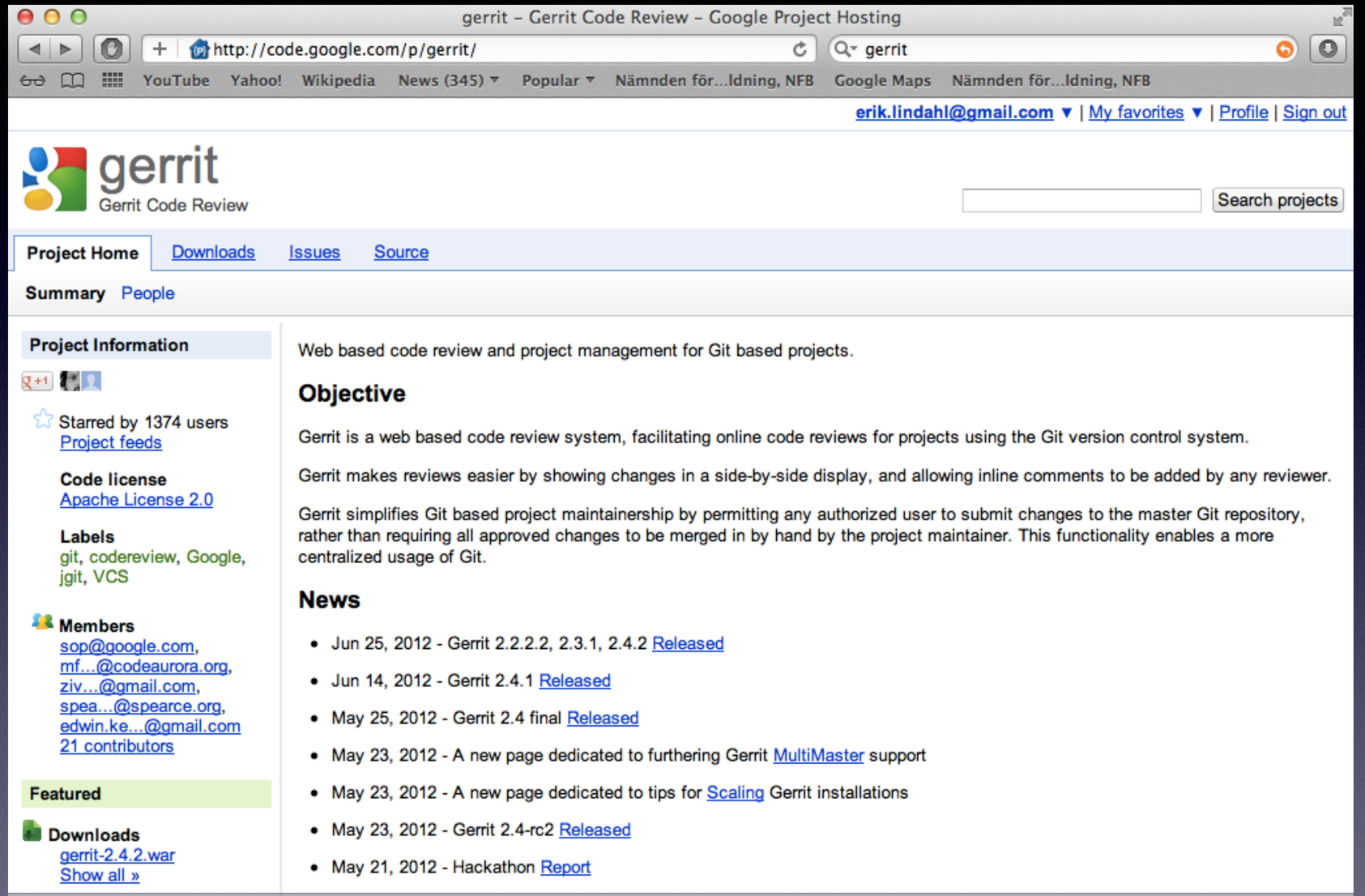
Commits - how code makes it into Gromacs

Who is allowed to write to your code repository?

Problems with developers who submit bad code

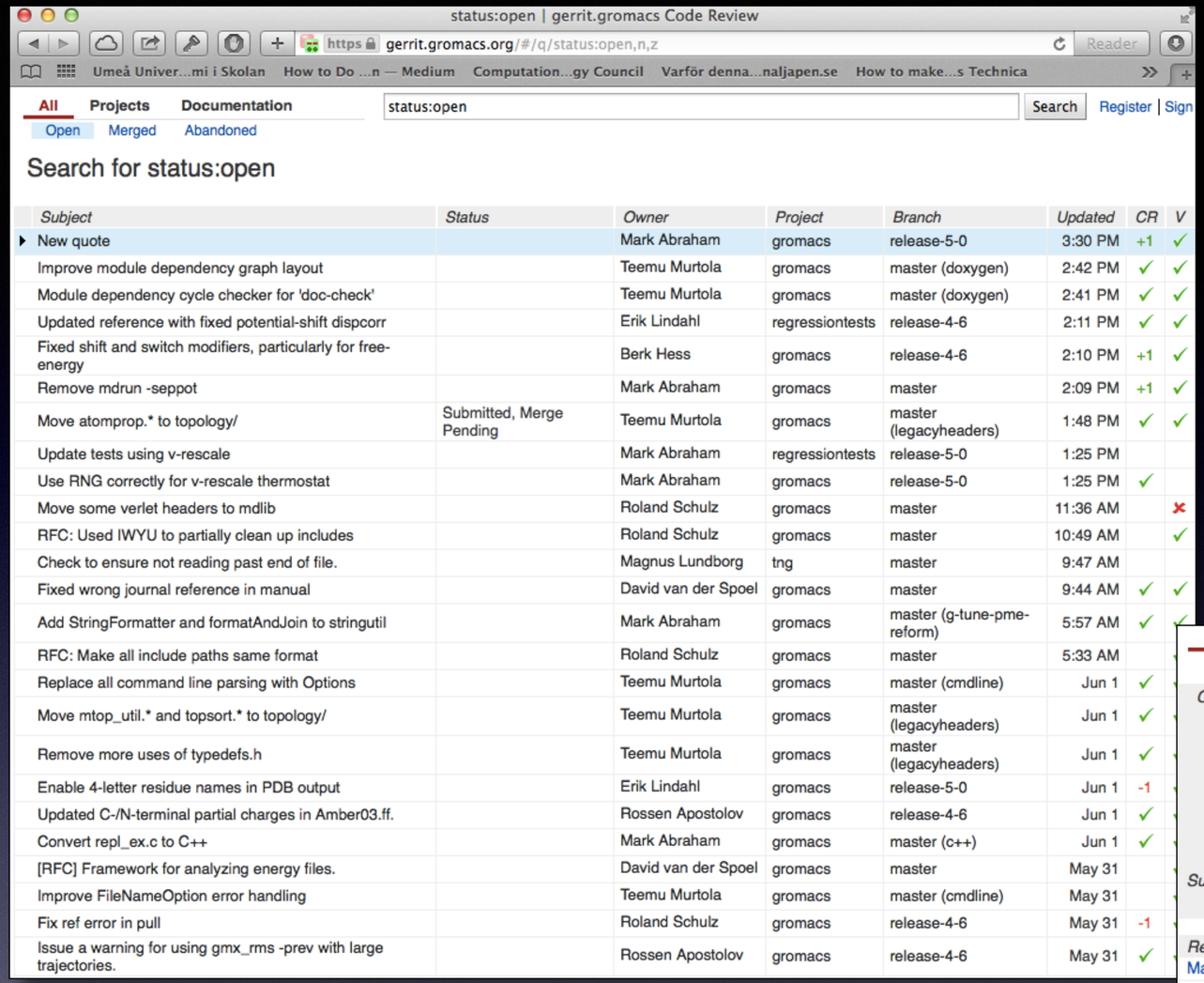
Such as this one

Gerrit Code Review



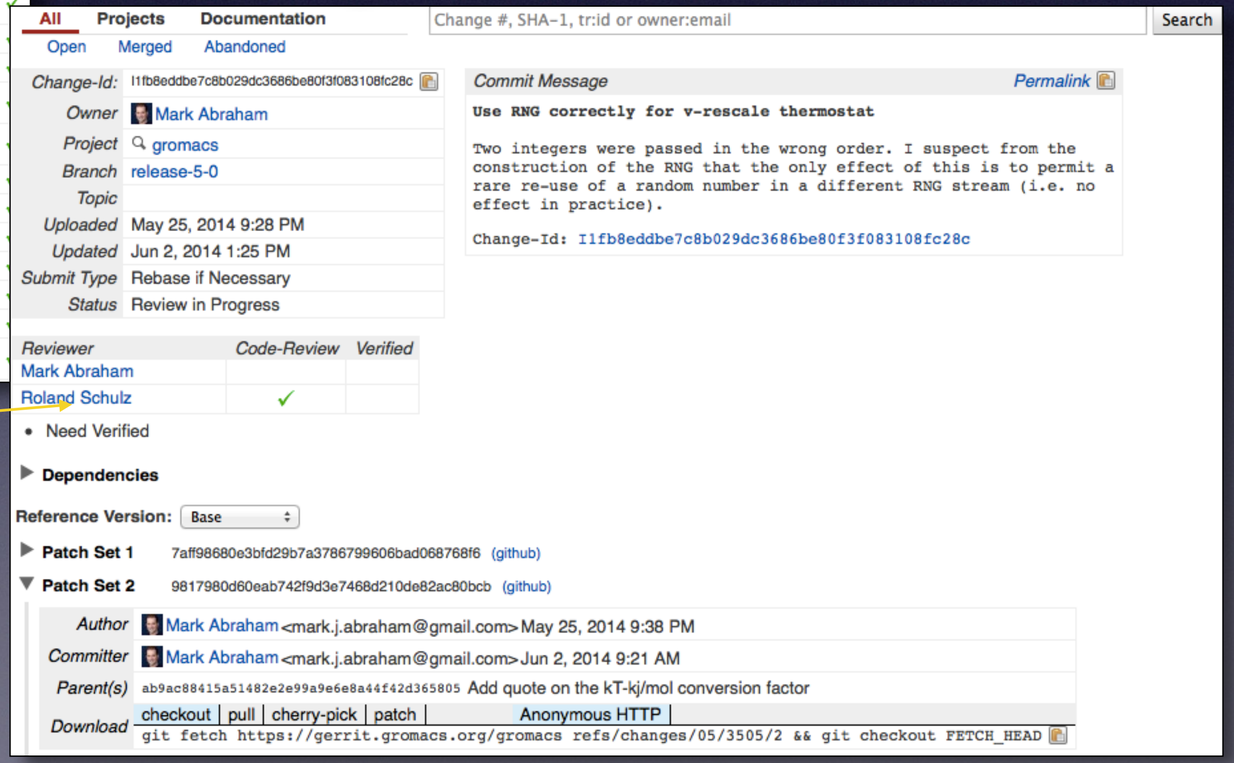
Nobody can commit directly to our central Git repo anymore

... which means we can allow anybody to commit in gerrit!



Multiple patches in-flight
Gerrit/git do dependency tracking, patches can be rebased onto others by hitting a rebase button, or even edited on-the-fly in the window

Extensive comments on code during review



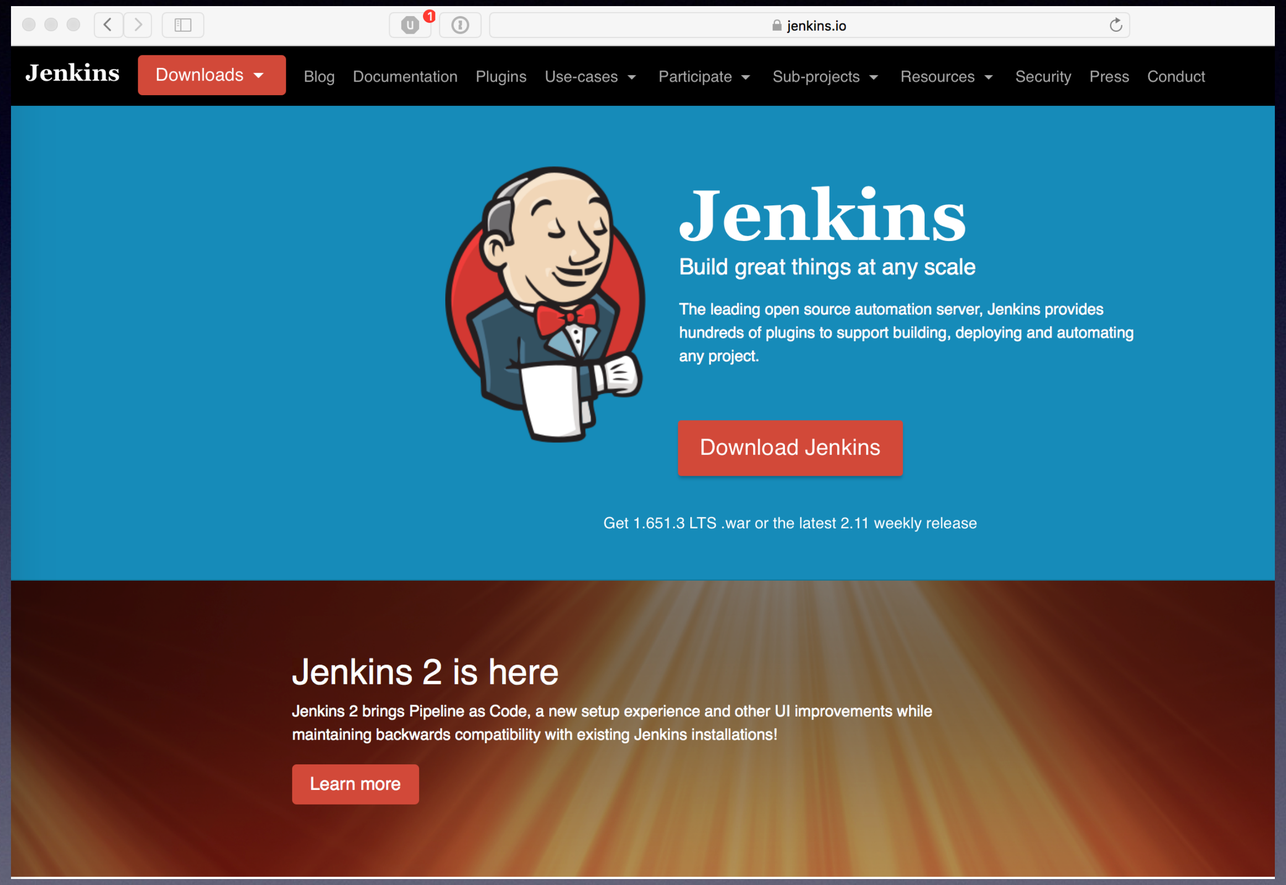
Roland has approved Mark's patch. Anybody can add comments. When two trusted developers say OK, the patch is committed.

Maintaining quality & avoiding breaking stuff

How do I make sure that *I* don’t make mistakes?

Jenkins Continuous Integration

https://jenkins.io



Every single commit is tested automatically on our build farm, including both builds and regression tests.

Results are integrated into the gerrit review

- Catches Cmake build errors
- Catches Google test unit test failures

GROMACS CI tests for every commit

- Unit Tests: Do modules reproduce reference values?
- Regression tests: Are previous simulation results identical?
- Clang AddressSanitizer: Catch simple memory errors
- Clang MemorySanitizer: Like Valgrind - memory debugging
- Clang/GCC ThreadSanitizer: Thread synchronization errors
- Clang Static Analyzer: Logical execution dependency errors
- Cppcheck: Another static analyzer
- Uncrustify: Proper code formatting, no tabs, brace standards?
- Doxygen: All classes/methods/arguments/variables documented?
- Coming: Performance regression testing

Configuration Matrix	bs-win2012r2	bs_gpu01	bs_mac	bs_mic	bs_nix-amd	bs_nix-amd_gpu	bs_nix1204	bs_nix1310	bs_nix1404
gcc-4.8 gpu cuda-7.0 cmake-3.8.1 mpi npme=1 nranks=2 openmp host=bs_nix1310									
gcc-7 gpu gpu_id=1 cuda-9.2 thread-mpi openmp cmake-3.6.1 release-with-assert simd=avx2_256 host=bs_nix1204									
gcc-7 tsan no-openmp fftpack cmake-3.10.0 host=bs_mic									
gcc-7 double mpi simd=avx_128_fma host=bs_nix1404									
gcc-6 x11 host=bs_mac									
clang-3.4 double simd=avx_128_fma thread-mpi no-openmp fftpack cmake-3.4.3 host=bs_nix-amd									
clang-6 no-openmp asan cmake-3.11.4 tidy host=bs_nix									
msvc-2017 openmp release-with-assert host=bs-win2012r2									
icc-18 no-thread-mpi double openmp mkl cmake-3.9.6 simd=none release host=bs_mic									
icc-18 openmp opencl clFFT-2.14 cuda-7.5 mpi release simd=avx2_256 host=bs_nix1310									
gcc-5 openmp simd=avx_128_fma opencl clFFT-2.14 amdappsdk-3.0 host=bs_nix-amd_gpu									

OPTIONS

Pre-submit GROMACS testing:

Changes cannot be committed in Gerrit until this matrix is all-green. Tests of a bunch of common compiler/OS/hardware/acceleration options.

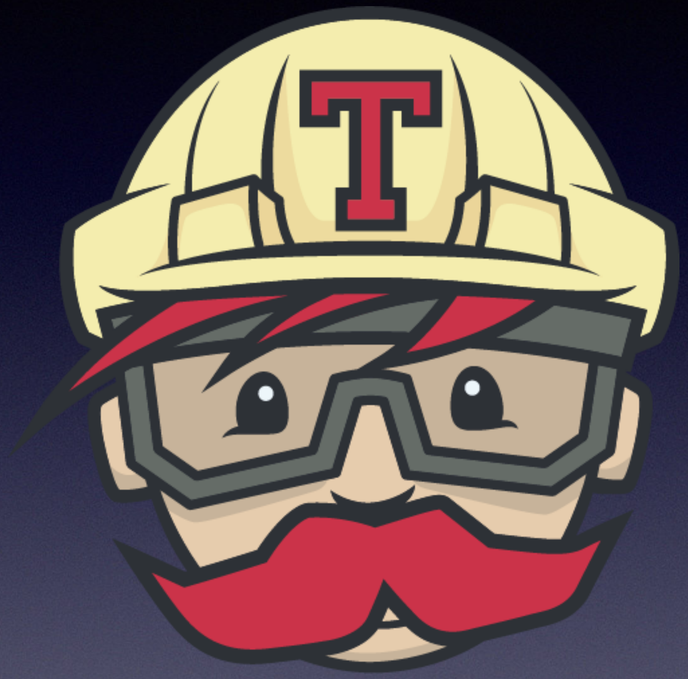
Post-submit GROMACS testing:

Rare hardware and longer-running performance tests are performed once each patch has been approved.

Configuration Matrix	docker-ubuntu-15.04	bs-win2012r2	bs_jetson_tk1	bs_jetson_tx1	bs_mac	bs_mic	bs_nix-amd	bs_nix-amd_gpu	bs_nix-tsan	bs_nix1204	bs_nix1310	bs_nix1404
gcc-5 simd=ARM_NEON release-with-assert host=bs_jetson_tk1												
gcc-5 simd=ARM_NEON_ASIMD release-with-assert host=bs_jetson_tx1												
gcc-7 mpi no-openmp fftpack mdrun-only host=bs_nix1404												
icc-18 simd=avx_256 npme=1 nranks=2 no-openmp double fftpack release host=bs_mic												
gcc-4.9 gpu cuda-7.0 openmp release-with-assert host=bs_mic												
clang-4 simd=sse4.1 openmp nranks=1 gpu cuda-8.0 clang_cuda host=bs_nix1204												
clang-5 openmp simd=avx_128_fma npme=1 nranks=2 mpi host=bs_nix-amd												
gcc-6 gpu npme=1 nranks=2 opencl cuda-7.5 simd=sse2 release host=bs_nix1310												
gcc-5 gpu nranks=4 gpu_id=1 cuda-8.0 no-hwloc release-with-assert host=bs_nix1204												
icc-16 msvc-2017 fftpack simd=avx2_256 release host=bs-win2012r2												
gcc-7 armhpc-18.2 openmp simd=ARM_NEON_ASIMD release host=bs_overdrive_1000												
armclang-18.2 armhpc-18.2 openmp simd=ARM_NEON_ASIMD release-with-assert host=bs_overdrive_1000												

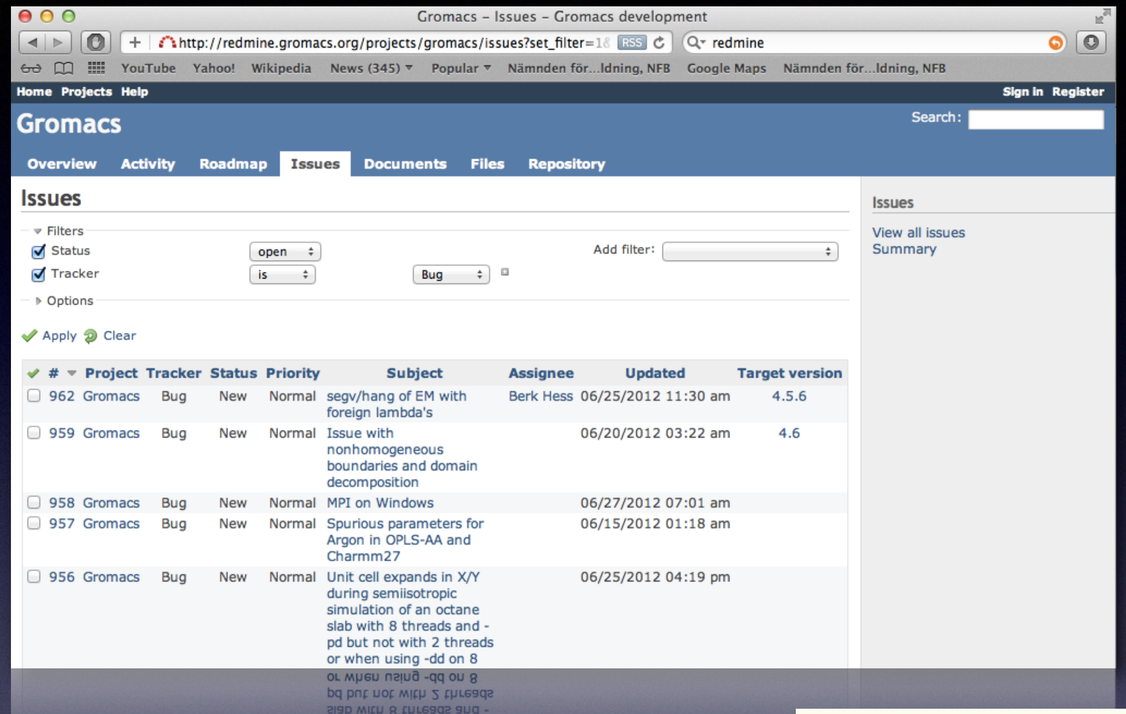
Travis CI

https://travis-ci.org



- Jenkins is *very* powerful, but you need to set it up yourself to do advanced stuff, and/or arrange access to special hardware
- If your needs are more modest, Travis-CI is a much simpler environment that offers *free* CI testing of open source GitHub repositories
- Of course this is enables for the IHPCSS-laplace repo: Every time I push an update, the code is built, followed by execution of the unit tests.
- If you look at the two badges at GitHub, green colors mean both the Travis CI and ReadTheDocs builds are OK.
- Suggested exercise: Clone/rename the repo, and turn on both Travis & ReadTheDocs automated builds in your version of it!

Redmine issue tracking



- Version 1.2.3 has bug X!
- Windows builds broke
- How is the work going on refactoring module Y?
- Should we improve scaling by method Z or W?

- Why did we decide to modify that loop in file F in git change Icfca5a?

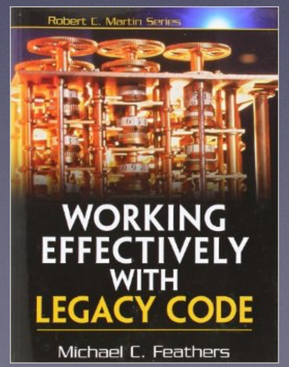
Automatic referencing in commit messages!

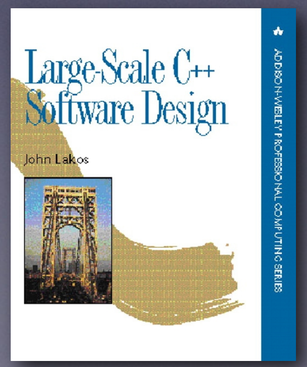
```
Closes #926 - Raw assembly code has been removed.
Refs #923 - Old kernels removed, new will be added shortly.
Fixes #914 - Cmake now does architecture-speficic optimization.
Fixes #912, #913
Fixes #857 - We detect rdtscp support with CPUID and use it if possible.
Fixes #750
Closes #537, #574 - Altivec is now deprecated.

Change-Id: Icfca5a940762f8d82ae67b59c65b2d2ac683256d
```

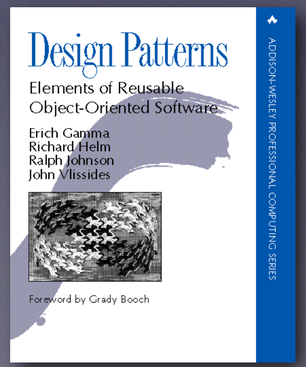
For IHPCSS/software-engineering, we use the simpler integrated issue tracker in GitHub, but this too supports automated referencing e.g. for closing bugs.

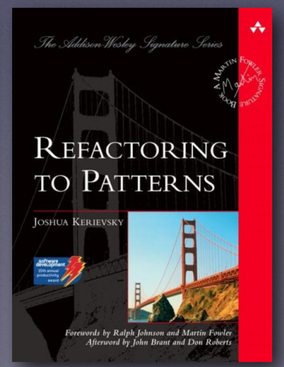
Some good reading

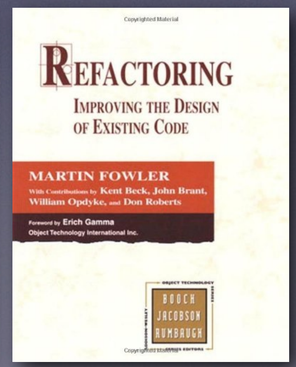
- Working effectively with legacy code [Michael Feathers]
- Large-scale C++ software design [John Lakos]
- Design Patterns - Elements of Reusable Object-oriented software [Gamma, Helm, Johnson, Vlissides] “Gang of four”
- Refactoring to Patterns [Joshua Kerievsky]
- Refactoring - improving the design of existing code [Martin Fowler]
- Effective C++ - 55 specific ways to improve your programs and design [Scott Meyers]
- Patterns for concurrent, parallel, and distributed systems: http://www.cs.wustl.edu/~schmidt/patterns-ace.html
- What everybody should know about floating-point math: http://randomascii.wordpress.com/category/floating-point/

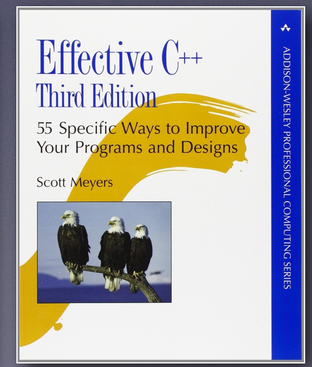










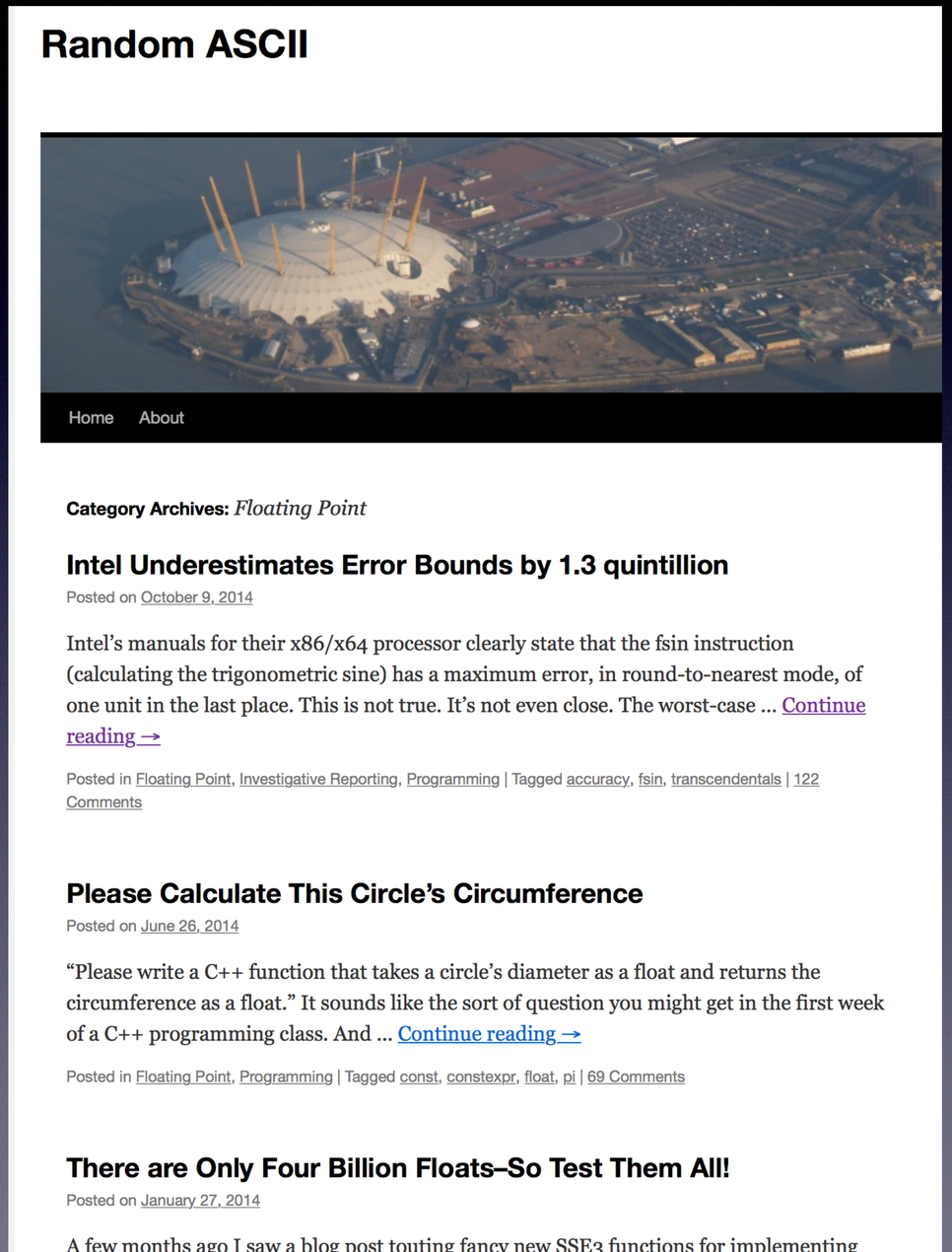


http://randomascii.wordpress.com/category/floating-point/

Series of blog posts by Bruce Dawson about IEEE754 floating point

You **should** read this if you are working with scientific codes using floating-point!

More worthwhile reading:
"What every computer scientist should know about floating-point arithmetic" [David Goldberg]



Random ASCII

Home About

Category Archives: *Floating Point*

Intel Underestimates Error Bounds by 1.3 quintillion

Posted on October 9, 2014

Intel's manuals for their x86/x64 processor clearly state that the fsin instruction (calculating the trigonometric sine) has a maximum error, in round-to-nearest mode, of one unit in the last place. This is not true. It's not even close. The worst-case ... Continue reading →

Posted in Floating Point, Investigative Reporting, Programming | Tagged accuracy, fsin, transcendentals | 122 Comments

Please Calculate This Circle's Circumference

Posted on June 26, 2014

"Please write a C++ function that takes a circle's diameter as a float and returns the circumference as a float." It sounds like the sort of question you might get in the first week of a C++ programming class. And ... Continue reading →

Posted in Floating Point, Programming | Tagged const, constexpr, float, pi | 69 Comments

There are Only Four Billion Floats–So Test Them All!

Posted on January 27, 2014

A few months ago I saw a blog post touting fancy new SSE3 functions for implementing

Use the source, Luke

First:

https://github.com/IHPCSS/software-engineering

Please DO steal this and use it as a template for your own project!

When that is not advanced enough:

http://www.gromacs.org

git://git.gromacs.org

http://gerrit.gromacs.org

http://redmine.gromacs.org

http://jenkins.gromacs.org

There are lots of other open programs out there too.
If you too are free software it is usually OK to reuse
their code in your project (if licenses match)!